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		THES=ASSIGNEE; PLUR=YES; OP=OR			
<u>L15</u>	L14 and l6		2	<u>L15</u>	
<u>L14</u>	l10 or l12 or l13		59	<u>L14</u>	
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<u>L13</u>	[PN]	(3648029 3786497 4121204 3921166 T904088)!	4	<u>L13</u>	

*DB=PGPB,USPT,DWPI; THES=ASSIGNEE; PLUR=YES;
OP=OR*

L12 ("20040263494"|"20050137765"|"20050141997"|"4221975"|"US20050137765A"|"WO 200288905A")
[ABPN1,NRPN,PN]

9 L12

*DB=PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD;
THES=ASSIGNEE; PLUR=YES; OP=OR*

L11 196 L11

*DB=PGPB,USPT,DWPI; THES=ASSIGNEE; PLUR=YES;
OP=OR*

L10 ("20040263494"|"20050137765"|"20050141997"|"4221975"|"US20050137765A"|"WO 200288905A")
[URPN]

46 L10

*DB=PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD;
THES=ASSIGNEE; PLUR=YES; OP=OR*

L9 20040263494 or 156 L9L8 L7 and (vehicle or car or automobile)1 L8L7 L6 not 1413 L7

(prox\$ near4 sens\$) and (sequen\$ with pattern\$) and

L6 (control\$ adj5 (device or apparatus or component or
system)) and (activat\$ near5 sequenc\$)13 L6L5 (prox\$ near2 sens\$) and (sequent\$ with pattern\$) and
(control\$ adj3 (device or apparatus or component or
system)) and (activat\$ near4 sequenc\$)4 L5L4 (prox\$ near2 sens\$) and (sequent\$ with pattern\$) and
(control\$ adj3 (device or apparatus or component or
system)) and (activat\$ near4 sequenc\$) and ((decre\$ or
incre\$) near3 direction\$)0 L4L3 led and (slid\$ with (control\$ or activat\$)) and (prox\$
near2 sens\$) and (sequent\$ with pattern\$) and (control\$
adj3 (device or apparatus or component or system)) and
(activat\$ near4 sequenc\$) and ((decre\$ or incre\$) near3
direction\$)0 L3(slid\$ with (control\$ or activat\$)) and (prox\$ near2
sens\$) and (sequent\$ with pattern\$) and (control\$ adj3

(device or apparatus or component or system)) and
L2 (activat\$ near4 sequenc\$) and ((decre\$ or incre\$) near3
direction\$) and @ad<=20031219 0 L2
L1 20050137765 2 L1

END OF SEARCH HISTORY

Results for "(sequen* <near/4> pattern*) <and> (prox* <near/4> sens*) <and> ((switch* ...)"

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Gdalyahu, Y.; Weinshall, D.;
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- 6. **Automatic gait recognition based on statistical shape analysis**

Liang Wang; Tieniu Tan; Weiming Hu; Huazhong Ning;
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Volume 12, Issue 9, Sept. 2003 Page(s):1120 - 1131
Digital Object Identifier 10.1109/TIP.2003.815251
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- 7. **Web mining in soft computing framework: relevance, state of the art and future dir**
Pal, S.K.; Talwar, V.; Mitra, P.;
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Kamimura, A.; Kurokawa, H.; Yoshida, E.; Murata, S.; Tomita, K.; Kokaji, S.;
Mechatronics, IEEE/ASME Transactions on
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- 10. **Unbalance and harmonics detection in induction motors using an optical fiber sen**
Corres, J.M.; Bravo, J.; Arregui, F.J.; Matias, I.R.;
Sensors Journal, IEEE
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- 11. **Force interaction and allocation for the legs of a walking vehicle**
Klein, C.; Tae-Sang Chung;
Robotics and Automation, IEEE Journal of [legacy, pre - 1988]
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- 13. **Shielding and electrical performance of silicon detector supermodules**
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Nuclear Science, IEEE Transactions on
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Digital Object Identifier 10.1109/TNS.2005.856902

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- 14. HMM based online handwriting recognition**
Jianying Hu; Brown, M.K.; Turin, W.;
[Pattern Analysis and Machine Intelligence, IEEE Transactions on](#)
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Derntl, M.; Hummel, K.A.;
[Pervasive Computing and Communications Workshops, 2005. PerCom 2005 Workshops](#)
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Digital Object Identifier 10.1109/PERCOMW.2005.60
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- 16. A hierarchical system structure for coordinated control of industrial manipulators**
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[Robotics and Automation, Proceedings. 1984 IEEE International Conference on](#)
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- 17. Dynamics of projective adaptive resonance theory model: the foundation of PART**
Yongqiang Cao; Jianhong Wu;
[Neural Networks, IEEE Transactions on](#)
Volume 15, Issue 2, March 2004 Page(s):245 - 260
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- 18. Distributed Data Streams Indexing using Content-Based Routing Paradigm**
Bulut, A.; Singh, A.K.; Vitenberg, R.;
[Parallel and Distributed Processing Symposium, 2005. Proceedings. 19th IEEE International](#)
04-08 April 2005 Page(s):94 - 94
Digital Object Identifier 10.1109/IPDPS.2005.170
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- 19. Amplitude spectrum-based gait recognition**
Guoying Zhao; Rui Chen; Guoyi Liu; Hua Li;
[Automatic Face and Gesture Recognition, 2004. Proceedings. Sixth IEEE International C](#)
17-19 May 2004 Page(s):23 - 28
Digital Object Identifier 10.1109/AFGR.2004.1301504
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- 20. Experimental validation of pulse contour methods for estimating stroke volume at**
Yinghong Yu; Jiang Ding; Lili Liu; Salo, R.; Spinelli, J.; Tockman, B.; Pochet, T.; Auricchio, F.;
[Engineering in Medicine and Biology Society, 1998. Proceedings of the 20th Annual International Conference of the IEEE](#)
29 Oct.-1 Nov. 1998 Page(s):401 - 404 vol.1
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L4: Entry 1 of 1

File: DWPI

Dec 7, 2006

DERWENT-ACC-NO: 2007-137409

DERWENT-WEEK: 200714

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TITLE: Satellite positioning system's e.g. global positioning system, receiver position locating method for use with e.g. cellular telephone, involves obtaining range-rate measurements at receiver with respect to set of satellites

INVENTOR: DIGGELEN, F V; VAN DIGGELEN, F

PATENT-ASSIGNEE: DIGGELEN F V (DIGGI), GLOBAL LOCATE INC (GLOBN)

PRIORITY-DATA: 2005US-0142824 (June 1, 2005)

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PATENT-FAMILY:

PUB-NO	PUB-DATE	LANGUAGE	PAGES	MAIN-IPC
<input type="checkbox"/> WO 2006130515 A2	December 7, 2006	E	000	
<input type="checkbox"/> US 20060273954 A1	December 7, 2006		013	G01S005/14

DESIGNATED-STATES: AE AG AL AM AT AU AZ BA BB BG BR BW BY BZ CA CH CN CO CR CU CZ DE DK DM DZ EC EE EG ES FI GB GD GE GH GM HR HU ID IL IN IS JP KE KG KM KN KP KR KZ LC LK LR LS LT LU LV LY MA MD MG MK MN MW MX MZ NA NG NI NO NZ OM PG PH PL PT RO RU SC SD SE SG SK SL SM SY TJ TM TN TR TT TZ UA UG US UZ VC VN YU ZA ZM ZW AT BE BG BW CH CY CZ DE DK EA EE ES FI FR GB GH GM GR HU IE IS IT KE LS LT LU LV MC MW MZ NA NL OA PL PT RO SD SE SI SK SL SZ TR TZ UG ZM ZW

APPLICATION-DATA:

PUB-NO	APPL-DATE	APPL-NO	DESCRIPTOR
WO2006130515A2	May 26, 2006	2006WO-US20568	
US20060273954A1	June 1, 2005	2005US-0142824	

INT-CL (IPC): G01S 5/14

ABSTRACTED-PUB-NO: US20060273954A

BASIC-ABSTRACT:

NOVELTY - The method involves measuring fractional pseudoranges from a remote receiver to a set of satellites, and obtaining an initial position at the remote receiver. The position of the remote receiver is computed using the fractional pseudoranges and the initial position. Range-rate measurements at the remote

receiver are obtained with respect to a set of satellites by obtaining Doppler measurements with respect to the set of satellites. The position is validated using the range-rate measurements.

DETAILED DESCRIPTION - An INDEPENDENT CLAIM is also included for an apparatus for locating a position comprising a satellite signal receiver for measuring fractional pseudoranges to a set of satellites and for obtaining range-rate measurements with respect to the set of satellites.

USE - Used for locating a position of a receiver of a satellite positioning system (SPS) e.g. global positioning system (GPS), wide area augmentation system (WAAS), European GALILEO system, SBAS, and Russian GLONASS system, that is connected with a server via a network e.g. wireless network such as a cellular telephone network, and a wired network such as Internet, in a position location system that is utilized with a mobile or wireless device e.g. cellular telephone, pager, laptop computer, and personal digital assistant (PDA).

ADVANTAGE - The method effectively performs a validation of the position of the receiver in the satellite position system.

DESCRIPTION OF DRAWING(S) - The drawing shows a flow diagram depicting an embodiment of a method for locating a position of a remote receiver.

ABSTRACTED-PUB-NO: US20060273954A

EQUIVALENT-ABSTRACTS:

CHOSEN-DRAWING: Dwg.2/5

DERWENT-CLASS: W06

EPI-CODES: W06-A03A5C;

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1. Document ID: US 20040263494 A1

L15: Entry 1 of 2

File: PGPB

Dec 30, 2004

PGPUB-DOCUMENT-NUMBER: 20040263494

PGPUB-FILING-TYPE: new

DOCUMENT-IDENTIFIER: US 20040263494 A1

TITLE: Location sensitive display device, system, and method of providing animation sequences

PUBLICATION-DATE: December 30, 2004

INVENTOR-INFORMATION:

NAME	CITY	STATE	COUNTRY
Poor, Kyle W.	Orlando	FL	US
Holzberg, Roger S.	Burbank	CA	US
Dietz, Paul H.	Hopkinton	MA	US
Stein, Lawrence P.	Windermere	FL	US
Swirsky, Robert	Sunnyvale	CA	US

US-CL-CURRENT: 345/204

2. Document ID: US 4221975 A

L15: Entry 2 of 2

File: USPT

Sep 9, 1980

US-PAT-NO: 4221975

DOCUMENT-IDENTIFIER: US 4221975 A

TITLE: Touch activated controller and method

Terms	Documents
L14 and L6	2

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